

Rate-Induced Bifurcations: Can We Adapting to a Changing Environment?

Part II

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Real world systems

- ▶ The compost-bomb instability

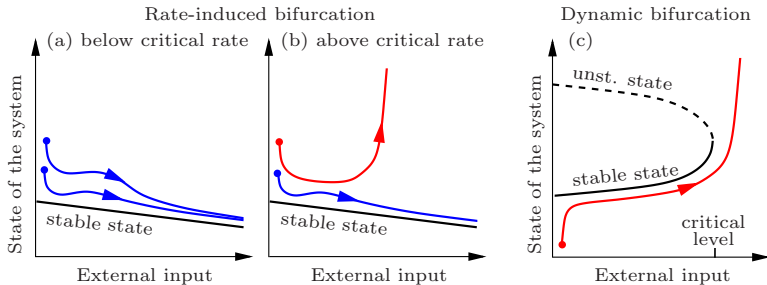
C. Luke & P. Cox 2011 *Eur. J. Soil Sci.* **62**, 5-12.

- ▶ The thermo-haline circulation with freshwater forcing

V. Lucarini, S. Calmanti & V. Artale 2005 *Climate Dynamics* **24**, 253-262.

- ▶ Type III neural excitability

J. Mitry, M. McCarthy, N. Kopell & and M. Wechselberger 2013 *J. Math. Neuro.* **3**, 12.



A trajectory **tracks** the continuously changing stable state or **destabilises**.

The mathematical description

$$\frac{dx}{dt} = f(x, \lambda(\epsilon t))$$

x system variable;

λ external input;

ϵ rate of change.

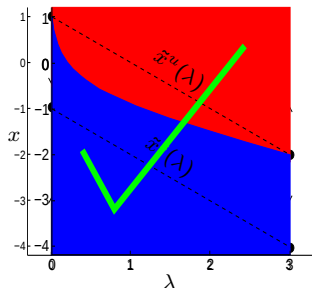
For every fixed value of λ there is a stable state $\tilde{x}(\lambda)$.

Questions

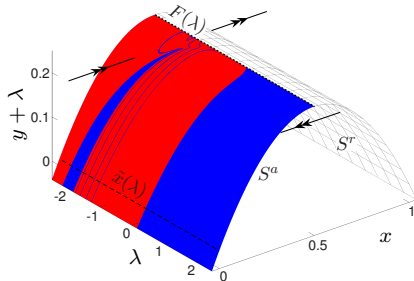
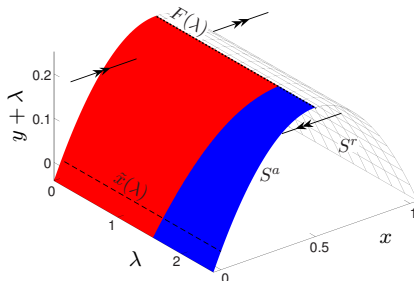
For different systems $f(x, \lambda(\epsilon t))$ and external inputs $\lambda(\epsilon t)$:

- ▶ Does the system have a critical rate ϵ_c ?
- ▶ Can we compute ϵ_c ?
- ▶ What is the threshold separating initial conditions that track $\tilde{x}(\lambda(\epsilon t))$ from those that destabilise?

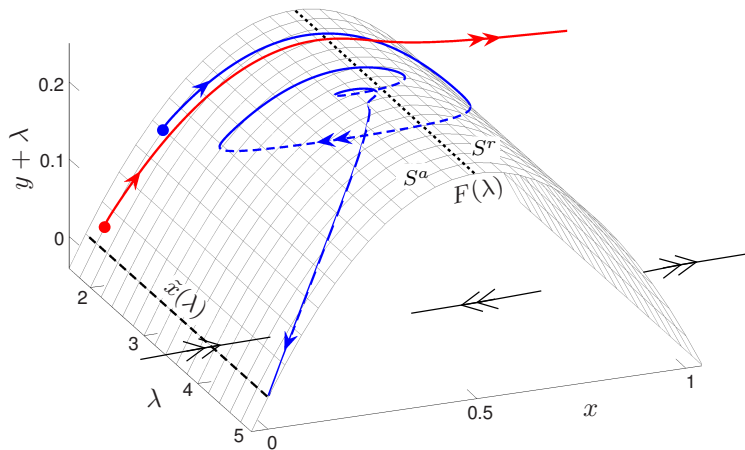
The obvious... and the non-obvious, both simple and complicated



tracks or destabilises



Thresholds in multiple timescale systems



A trajectory **tracks** $\tilde{x}(\lambda)$
or **destabilises** and moves away in the fast x -direction.

Analysing multiple timescale systems

Fix λ , $0 < \delta \ll 1$ and $t = \delta T$.

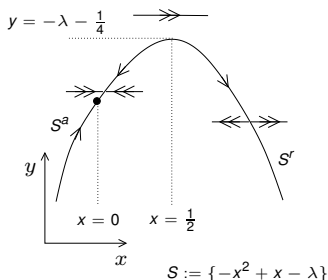
$$\delta \frac{dx}{dt} = y + \lambda + x(x - 1)$$

$$\frac{dy}{dt} = -x$$

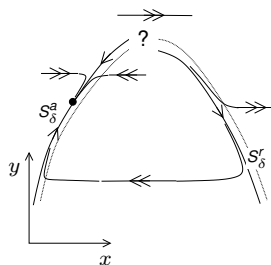
$$\frac{dx}{dT} = y + \lambda + x(x - 1)$$

$$\frac{dy}{dT} = -\delta x$$

$\delta = 0$



$\delta \neq 0$



Thresholds in multiple timescale systems

$$\begin{aligned}\delta \frac{dx}{dt} &= f(x, y, \lambda, \delta) \\ \frac{dy}{dt} &= g(x, y, \lambda, \delta) \\ \frac{d\lambda}{dt} &= \epsilon h(\lambda)\end{aligned}$$

Assumptions:

- ▶ 1 fast and 2 slow variables:
 $0 < \delta \ll \epsilon < 1$.
- ▶ The critical manifold S has a fold F tangent to the fast x direction:

$$\frac{\partial f}{\partial x} = 0, \frac{\partial^2 f}{\partial x^2} \neq 0.$$

$$S := \{f(x, y, \lambda, 0) = 0\}$$

- ▶ For fixed λ there is single curve of stable states $\tilde{x}(\lambda)$ close to the fold.

Thresholds in multiple timescale systems

So,

$$\begin{aligned}\delta \frac{dx}{dt} &= f(x, y, \lambda, \delta) \\ \frac{dy}{dt} &= g(x, y, \lambda, \delta) \\ \frac{d\lambda}{dt} &= \epsilon h(\lambda)\end{aligned}$$

- ▶ The critical manifold S is a 2D.
- ▶ The fold F separates S into an attracting part S^a and repelling part S^r .
- ▶ The static stable state $\tilde{x}(\lambda)$ is on S^a .

$$S := \{f(x, y, \lambda, 0) = 0\}$$

Also, for small $\delta > 0$, S^a and S^r perturb to nearby 2D manifolds S_δ^a and S_δ^r with the same attractivity (Fenichel, 1971).

Look at the system on the critical manifold

Project onto S:

$$\begin{aligned}\delta \frac{dx}{dt} &= f(x, y, \lambda, \delta) & -\frac{\partial f}{\partial x} \Big|_S \frac{dx}{dt} &= \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_S \\ \frac{dy}{dt} &= g(x, y, \lambda, \delta) & \frac{d\lambda}{dt} &= \epsilon h|_S \\ \frac{d\lambda}{dt} &= \epsilon h(\lambda)\end{aligned}$$

$$S := \{f(x, y, \lambda, 0) = 0\}$$

Look at the system on the critical manifold

Project onto S:

$$\begin{aligned}\delta \frac{dx}{dt} &= f(x, y, \lambda, \delta) \\ \frac{dy}{dt} &= g(x, y, \lambda, \delta) \\ \frac{d\lambda}{dt} &= \epsilon h(\lambda)\end{aligned}$$

$$\begin{aligned}-\frac{\partial f}{\partial x}\bigg|_S \frac{dx}{dt} &= \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda}\right)\bigg|_S \\ \frac{d\lambda}{dt} &= \epsilon h|_S\end{aligned}$$

Desingularise by $dt = -ds(\partial f / \partial x)|_S$:

$$S := \{f(x, y, \lambda, 0) = 0\}$$

$$\begin{aligned}\frac{dx}{ds} &= \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda}\right)\bigg|_S \\ \frac{d\lambda}{ds} &= -\epsilon \left(h \frac{\partial f}{\partial x}\right)\bigg|_S\end{aligned}$$

Look at the system on the critical manifold

$$\delta \frac{dx}{dt} = f(x, y, \lambda, \delta)$$

$$\frac{dy}{dt} = g(x, y, \lambda, \delta)$$

$$\frac{d\lambda}{dt} = \epsilon h(\lambda)$$

Project onto S:

$$-\frac{\partial f}{\partial x} \Big|_S \frac{dx}{dt} = \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_S$$

$$\frac{d\lambda}{dt} = \epsilon h|_S$$

Desingularise by $dt = -ds(\partial f / \partial x)|_S$:

Folded singularities:

$$\left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_S = 0$$

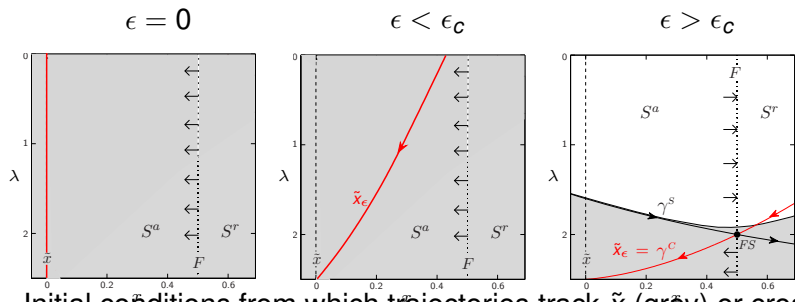
$$-\frac{\partial f}{\partial x} \Big|_S = 0.$$

$$\frac{dx}{ds} = \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_S$$

$$\frac{d\lambda}{ds} = -\epsilon \left(h \frac{\partial f}{\partial \lambda} \right) \Big|_S$$

Existence of critical rates

There is a critical rate if there is a folded singularity.



Initial conditions from which trajectories track $\tilde{x}$ (grey) or cross F and destabilise (white).

Existence of critical rates

There is a critical rate if there is a folded singularity.

There is a critical rate ϵ_c if for some point (x, y, λ) at time t both

$$\left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_F = 0$$

and

$$\frac{d}{d\epsilon} \left(g \frac{\partial f}{\partial y} + h \frac{\partial f}{\partial \lambda} \right) \Big|_F \neq 0.$$

Non-obvious thresholds

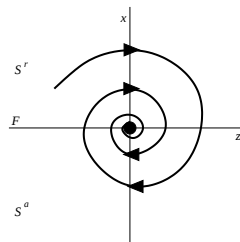
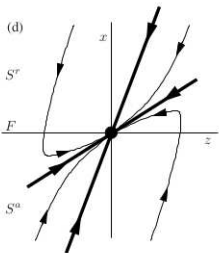
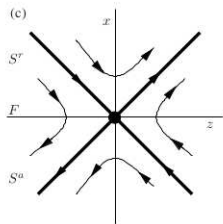
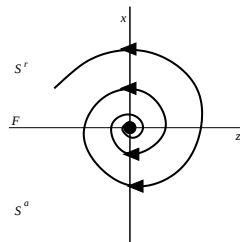
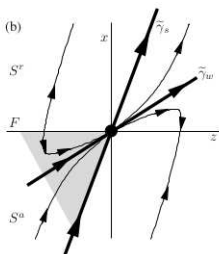
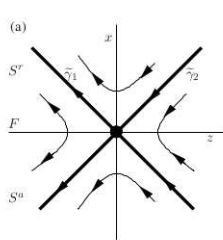
There is a critical rate if there is a folded singularity.

There maybe a **threshold** seperating the initial conditions from which trajectories track $\tilde{x}$ (grey), and destabilise (white).

Classification of folded singularities

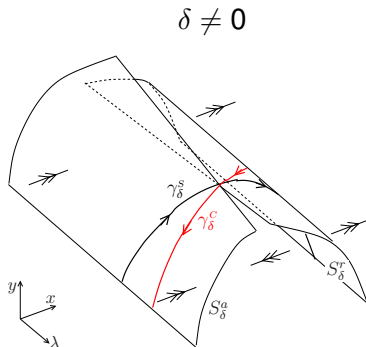
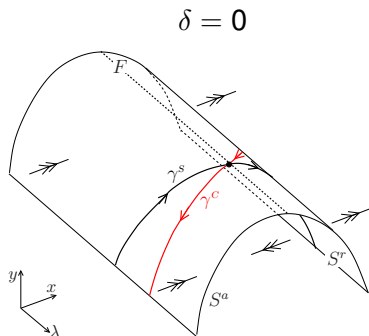
In the desingularised system time is reverse on S^r .

Canards γ go from S^a to S^r along eigendirections.



Along the fold F when $\delta \neq 0$

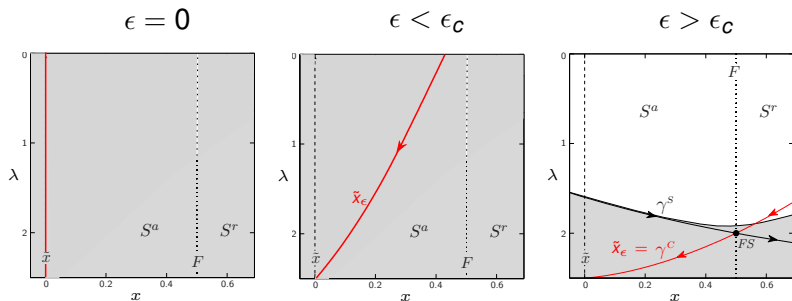
Canard γ_δ^S persists as a transverse (robust) intersection of S_δ^a and S_δ^r , (Szmolyan, 2001). Canards act as separatrices.



Simple threshold with an isolated folded saddle

$$\delta \frac{dx}{dt} = y + \lambda + x(x - 1); \quad \frac{dy}{dt} = -x; \quad \frac{d\lambda}{dt} = \epsilon(\lambda_{\max} - \lambda).$$

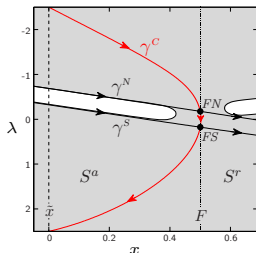
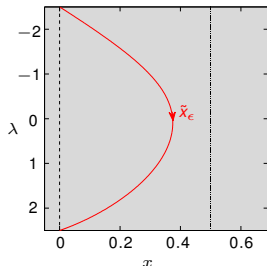
$$\epsilon_c = \frac{1}{2\lambda_{\max}}.$$



Non-obvious threshold γ_δ^S separates initial conditions that track $\tilde{x}$ (grey) or destabilise (white).

Complicated threshold after a folded saddle-node bifurcation

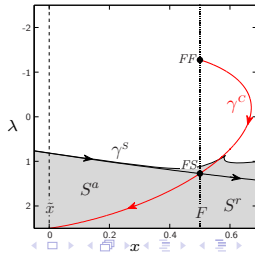
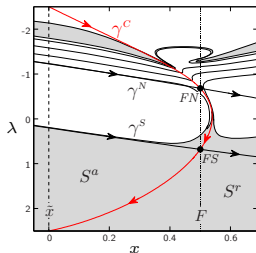
$$\delta \frac{dx}{dt} = y + \lambda + x(x-1); \quad \frac{dy}{dt} = -x; \quad \frac{d\lambda}{dt} = \epsilon(\lambda_{\max}^2 - \lambda^2)/\lambda_{\max}.$$



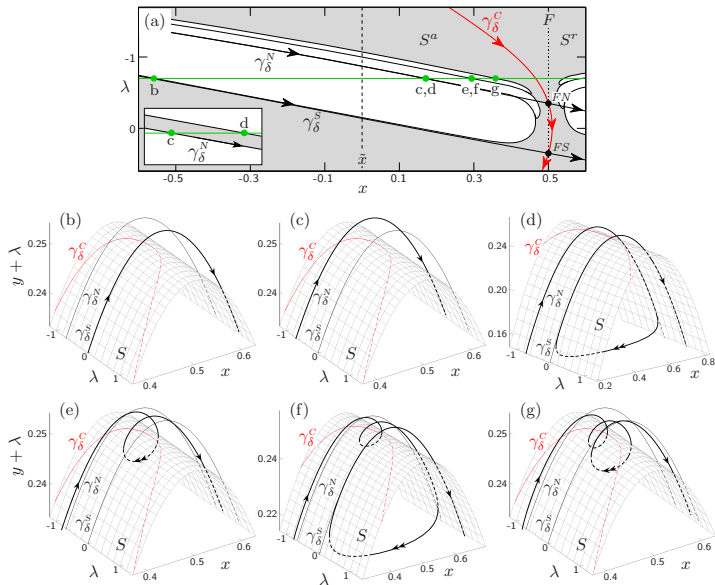
$$\epsilon_c = \frac{1}{2\lambda_{\max}}.$$

Panel 1: $\epsilon < \epsilon_c$

Panels 2-4: $\epsilon > \epsilon_c$

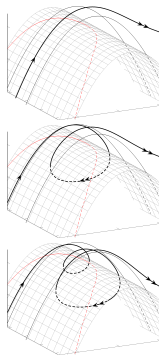


Composite canards form the boundary

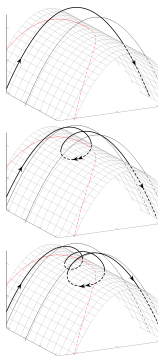


Composite canards form the boundary

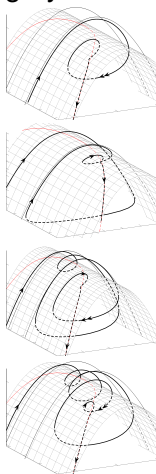
white ->



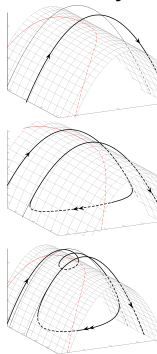
boundary ->



grey ->



boundary



Conclusions

Rate-induced bifurcations are of key importance in many real-world system. We seek to identify **critical rates** and **instability thresholds** in a range of systems.

Obvious rate-induced bifurcations: find a hetroclinic connection.

Non-obvious rate-induced bifurcations: use geometric singular perturbation theory, find folded singularities and canards:

- ▶ Existence results for critical rates and instability thresholds.
- ▶ Find a new complicated **banded threshold**.
- ▶ Identify the structure with new **composite canards**.

Bibliography

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- ▶ J. Mitry, M. McCarthy, N. Kopell, and M. Wechselberger “Excitable neurons, firing threshold manifolds and canards” *J. Math. Neuro.* **3**, 12 (2013).
- ▶ C. K. R. T. Jones, “Geometric singular perturbation theory”, in *Dynamical Systems*, Lecture Notes in Mathematics Vol. 1609 (Springer, Berlin Heidelberg, 1995).
- ▶ M. Desroches, J. Guckenheimer, B. Krauskopf, C. Kuehn, C. H. Osinga, and M. Wechselberger, “Mixed mode oscillations with multiple time scales”, *SIAM Review* **54**, 211 (2012).