Attractors and attracting measures

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joint with Pete Ashwin

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The purpose of this talk is not just to explain some of what I've been thinking about with Pete, but also to get some feedback and learn.

 $\rightarrow\,$ I have pretty much no experience with smooth ergodic theory.

I will probably be "asking" at least as many questions as I "answer".

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Motivation

Deterministic model of a climate system "without climate change":

- autonomous DE $\dot{x} = F(x)$ on some state space M, \ldots
 - autonomous since climate parameters are not changing;
 - but there may be different regions of M corresponding to "qualitatively different" climate scenarios, so:
- ... with some given "attractor" $A \subset M$ representing a stable qualitative state of the climate system.

E.g. AMOC could be described by an ODE $\dot{x} = F(x)$ with an attractor A_{on} corresponding to the "on" state of the AMOC (while there is another attractor A_{off} corresponding to a qualitatively different stable state of the AMOC, the "off" state).

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Motivation

Without "climate change", the quantitative state of the climate is always changing!

 \Rightarrow the attractor A is not a single point.

Leads to the question:

"If I observe this deterministic climate system at some 'random' time t that has nothing to do with the state of the climate itself, what is the probability distribution for the current quantitative state x(t) of the climate?"

Note:

- This would be a probability distribution supported on *A*.
- If *A* is "chaotic", then the answer is unaffected by observations made a sufficiently long time ago.



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Motivation

Problems:

- When is there a well-defined answer μ to this question?
- In what ways can μ be numerically simulated?
- Introduce climate change:

$$\dot{x}(t) = F_{\lambda(t)}(x(t)), \quad \lim_{t \to -\infty} F_{\lambda(t)} = F$$

- → evolve *A* forward from time $-\infty$ to get a set-valued trajectory *A*(*t*) equipped at each time *t* with the corresponding probability distribution $\mu(t)$;
- → but this doesn't mean anything—how do we give this rigorous meaning and simulate it?
- → if this system exhibits *"partial tipping"* then we use $\mu(t)$ to define the probability of tipping [Ashwin & N., submitted]

Although the goal is this "climate-changing" case, we're still trying to understand aspects of the autonomous case.



Motivation Axiom A attractors "Attracting measures"

Axiom A attractors

M – compact Riemannian manifold m – Lebesgue measure $(f^t)_{t \in \mathbb{R}}$ – solution flow for an autonomous ODE on M

An Axiom A attractor $A \subset M$ is a chaotic attractor with very nice "hyperbolicity" properties.

[Bowen & Ruelle, 1975]¹ Under weak conditions, given an Axiom A attractor *A* with "basin of attraction"

$$B_{\mathcal{A}} := \{ x_0 \in \mathcal{M} : \mathcal{d}(f^t x_0, \mathcal{A}) \to 0 \text{ as } t \to \infty \},\$$

A is the support of an ergodic invariant probability measure μ_A with the following two properties:

¹Analogous result for discrete-time maps in [Ruelle, 1976].

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Axiom A attractors

1 [BR75, Thm. 5.1] For *m*-a.e. $x_0 \in B_A$,

$$rac{1}{t}\int_0^t \delta_{f^s x_0} \, ds \stackrel{ ext{weakly}}{
ightarrow} \mu_{\mathcal{A}} \ ext{as} \ t
ightarrow \infty.$$

 \rightarrow LHS = law of x(T) for $T \sim \text{Unif}(0, t)$, given $x(0) = x_0$.

Property 1 is analogous to ergodicity: a prob. meas. μ is ergodic iff for μ -a.e. $x_0 \in M$,

$$\frac{1}{t} \int_0^t \delta_{f^s x_0} \, ds \stackrel{\text{weakly}}{\to} \mu.$$

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Heuristic meaning of "*m*-a.e.": your i.c. has to be "infinitely unlucky" to be a counterexample.

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2 [BR75, Thm. 5.3] For every p.m. $\nu_0 \ll m$ with $\nu_0(B_A) = 1$,

$$f^t
u_0 \stackrel{\mathsf{weakly}}{
ightarrow} \mu_{\mathcal{A}} ext{ as } t
ightarrow \infty.$$

 \rightarrow LHS = law of x(t) for $x(0) \sim \nu_0$.

Property 2 is analogous to mixing: a p.m. μ is mixing iff \forall p.m. $\nu_0 \ll \mu$,

$$f^t
u_0 \stackrel{\text{weakly}}{\to} \mu.$$
 (or strongly)

(**Remark.** mixing \Rightarrow ergodic.)

Heuristic meaning of " $\nu_0 \ll m$ ": the initial distribution ν_0 respects the notion of an "infinitely unlucky" result for x(0).

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The analogy between Property 2 and mixing can be understood in terms of decay of "classical correlations" vs. decay of "operational correlations" (e.g. [Baladi *et al.*, 2002]):

• An invariant p.m. μ is mixing iff $\forall g_1, g_2 \in C_b(M, \mathbb{R})$,

$$\operatorname{Cov}_{\mu}[g_1,g_2\circ f^t] = \int g_1(x)g_2(f^tx)\,\mu(dx) - \int g_1\,d\mu \int g_2\,d\mu \,\rightarrow \,0.$$

• Property 2 can be re-expressed as: $\forall g_1, g_2 \in C_b(B_A, \mathbb{R}),$

$$OC(g_1, g_2, t) := \int_{B_A} g_1(x) g_2(f^t x) m(dx) - \int_{B_A} g_1 dm \int g_2 d\mu_A \to 0.$$

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Axiom A attractors

Note: in [BR75], μ_A is constructed in Sec. 3; then Thms. 5.1 and 5.3 are separately proved based on material developed prior to Sec. 5.

Remark:

- Pr. 1 holds in the general setting of [BR75].
- Pr. 2 holds under mild extra assumption: the unstable manifold of each point in *A* is dense in *A*.
- \rightarrow Extra assumption only enters via the fact that <u>it implies μ_A is mixing</u>.

So [BR75, Thm. 5.3] "really" says: $\mu_A \text{ mixing} \Rightarrow \mu_A \text{ has Pr. 2}$.



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"Attracting measures"

Property 1: "physical measures"

ightarrow extensively studied in more general settings

Property 2: ???

 \rightarrow I will call such measures attracting measures



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"Attracting measures"

When A is a Lebesgue null set:

- mixing—purely in and of itself—may not be of much physical relevance;
- "attracting" is probably the more physically accessible notion of mixing dynamics [Baladi *et al.*, 2002];
- and yet it seems that attracting measures are under-appreciated and/or under-studied!
- E.g. the Lorenz system
 - has a chaotic attractor A supporting a physical measure μ_A [Tucker, 2002];
 - μ_A is mixing at an exponential rate [Araújo & Melbourne, 2016];
 - but is it known whether μ_A is attracting??



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What I will do in this talk

l will

- present definitions of attractors, physical measures and attracting measures in a generalised setting;
- present a generalisation of [BR75, Thm. 5.3];
- raise several questions along the way and at the end.

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General setting Physical and attracting measures Attractors

My generalised setting

- *M* Riemannian manifold
- m Lebesgue measure
- d geodesic distance
- $(f^t)_{t\geq 0}$ continuous semiflow of C^1 local diffeomorphisms

Actually, I can make it even more general (purely topological):

- M Polish space
- m locally finite measure of full support
- d metrisation of the topology of M

 $(f^t)_{t\geq 0}$ – continuous semiflow of open mappings $f^t: M \to M$ admitting a well-defined transfer operator w.r.t. *m* that locally respects boundedness.



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Physical and attracting measures

A p.m. μ whose support A is compact is called a(n)

• physical measure if \exists nbhd $U \supset A$ s.t. for *m*-a.e. $x_0 \in U$,

$$\frac{1}{t}\int_0^t \delta_{f^s x_0} \, ds \stackrel{\text{weakly}}{\to} \mu;$$

• attracting measure if \exists nbhd $U \supset A$ s.t. for each p.m. $\nu_0 \ll m$ with $\nu_0(U) = 1$,

$$f^t \nu_0 \stackrel{\text{weakly}}{\to} \mu.$$

I will generalise the proof of [BR75, Thm. 5.3] to obtain general conditions under which mixing implies attracting.



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Attractors

A compact set $A \subset M$ with $f^t A = A$ for all $t \ge 0$ is called a • pointwise attractor if \exists nbhd U s.t.

 $d(f^t x_0, A) \rightarrow 0$ for each $x_0 \in U$;

• uniform attractor if \exists nbhd U s.t.

 $d(f^t x_0, A) \rightarrow 0$ uniformly across $x_0 \in U$;

• pointwise attractor via stable manifolds if \exists nbhd *U* and $\pi: U \rightarrow A$ [w.l.o.g. Lebesgue-measurable] s.t.

$$d(f^t x_0, f^t \pi(x_0))
ightarrow 0$$
 for each $x_0 \in U$;

• uniform attractor via shadowing if \exists nbhd U s.t. $\forall \varepsilon > 0$, $\exists \pi_{\varepsilon} : U \rightarrow A$ s.t. for suff. large t,

$$\sup_{x_0 \in U} d(f^t x_0, f^t \pi_{\varepsilon}(x_0)) < \varepsilon.$$





An Axiom A attractor is both a pointwise via stable manifolds and uniformly via shadowing [BR75, Prop. 4.4].

Questions:

- What about "uniform via stable manifolds"?
 - i.e. does there exist nbhd U and $\pi: U \rightarrow A$ s.t.

 $d(f^t x_0, f^t \pi(x_0)) \rightarrow 0$ uniformly across $x_0 \in U$?

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2 Can π (in def'n of pointwise via stable manifolds) be chosen s.t. $\pi(m|_U) \ll \mu_A$?

A trivial result A maybe more useful result

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A trivial result

Proposition

Suppose we have p.m. μ whose support A is a pointwise attractor via stable manifolds.

Suppose (U, π) be chosen s.t. $\pi(m|_U) \ll \mu$.

If μ is mixing then μ is attracting.

Using our further-above characterisation of mixing, the proof is a trivial application of the dominated convergence theorem.

But I suspect that this result is useless (i.e. conditions typically don't hold or are very difficult to verify)??

A trivial result A maybe more useful result

A maybe more useful result

Theorem (generalising [BR75, Thm. 5.3])

Suppose we have p.m. μ whose support A is a uniform attractor via shadowing.

Suppose μ is mixing. Suppose μ also satisfies (*): \exists arbit'ly small $\varepsilon > 0$ s.t. one can find an unbounded set $\mathcal{T} \subset [0, \infty)$ with

$$\inf_{T \in \mathcal{T}, x \in \mathcal{A}} \frac{\mu(y \in \mathcal{A} : d(f^t x, f^t y) < \varepsilon \ \forall t \in [0, T])}{m(y \in \mathcal{M} : d(f^t x, f^t y) < 3\varepsilon \ \forall t \in [0, T])} > 0$$

Then μ is attracting.

[BR75] uses 2ε in place of 3ε (and verifies (*) in Cor. 4.6), but the proof doesn't seem to work with 2ε .



Some further questions

- Can we find settings outside of the Axiom A setting in which the Theorem can be applied?
- Can the conditions of the Theorem be weakened/modified so as to be more easily applicable beyond the Axiom A setting?
- In particular, might it be the case generally that every mixing physical measure is attracting?



Some further questions

- It is known that if a probability measure μ is an SRB measure in the sense of [Young, 2002], then it is "physical" under a weaker definition where the neighbourhood U may now be any *m*-positive-measure set [Pugh & Shub, 1989].
- \hookrightarrow If a probability measure μ is an SRB measure in the sense of [Young, 2002] and is also mixing, does it follow that μ is an "attracting measure", at least under a weaker definition where the neighbourhood *U* may now be any *m*-positive-measure set?

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Thank you.

